1	Updraft Vertical Velocity Observations and Uncertainties in High Plains Supercells Using
2	Radiosondes and Radars AM METER AM
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Abstract

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Observations of the air vertical velocities (w_{air}) in supercell updrafts are presented, including uncertainty estimates, from radiosonde GPS measurements in two supercells. These in situ observations were collected during the Colorado State University Convective CLoud Outflows and UpDrafts Experiment (C³LOUD-Ex) in moderately unstable environments in Colorado and Wyoming, USA. Based on the radiosonde accelerations, instances when the radiosonde balloon likely burst within the updraft are determined, and adjustments are made to account for the subsequent reduction in radiosonde buoyancy. Before and after these adjustments, the maximum estimated w_{air} values are 36.2 and 49.9 m s⁻¹, respectively. Radar data are used to contextualize the in situ observations and suggest that most of the radiosonde observations were located several kilometers away from the most intense vertical motions. Therefore, the radiosonde-based wair values presented likely underestimate the maximum values within these storms due to these sampling biases, as well as the impacts from hydrometeors, which are not accounted for. When possible, radiosonde-based wair values were compared to estimates from dual-Doppler methods and from parcel theory. When the radiosondes observed their highest w_{air} values, dual-Doppler methods generally produced 15-20 m s⁻¹ lower w_{air} for the same location, which could be related to the differences in the observing systems' resolutions. In situ observations within supercell updrafts, which have been limited in recent decades, can be used to improve our understanding and modeling of storm dynamics. This study provides new in situ observations, as well as methods and lessons that could be applied to future field campaigns.

1. Introduction

Supercell updrafts contain some of the most intense vertical air velocities (hereafter, w_{air})
in the atmosphere (e.g., Musil et al. 1986; Lehmiller et al. 2001; DiGangi et al. 2016). The
magnitude and vertical structure of w_{air} within supercell updrafts control many atmospheric
processes, including the production of severe hail (e.g., Browning and Foote 1976; Heymsfield
and Musil, 1982) and the transport of atmospheric constituents from the boundary layer to the
upper troposphere and stratosphere (e.g., Foote and Fankhauser 1973; Mullendore et al. 2005).
Due to the strong vertical velocities in supercell updrafts, cloud droplets do not have enough time
to grow to sizes that can be observed by most radars. Supercell updrafts can therefore be clearly
identified in radar data as regions with lower reflectivity in the lower and middle tropospheric
levels, laterally and vertically bounded by higher reflectivity, known initially as vaults and later
as weak echo regions or bounded weak echo regions (WERs or BWERs; Browning and Ludlam
1962; Chisholm 1970; Marwitz and Berry 1971; Chisholm 1973). Despite supercell updrafts'
importance for atmospheric processes, these updrafts have seldom been observed in situ.
The first of these infrequent in situ observations of the magnitudes of supercell updraft
velocities came from armored aircraft penetrations through the WERs (Marwitz and Berry 1971;
Heymsfield and Musil 1982). These observations were usually made near cloud base and in the
inflow air ahead of the supercell and were typically taken in the High Plains of the U.S. and
Canada. These initial in situ observations generally resulted in estimates of w_{air} in the 15-30 m s ⁻¹
range. One research flight into the WER of a supercell in Montana at ~7 km above mean sea
level (AMSL) observed w_{air} as high as 50 ± 5 m s ⁻¹ (Musil et al. 1986). Despite the continued
need for in situ observations of deep convection, the last U.S. storm-penetrating research aircraft
was retired without replacement in 2005 (Geerts et al. 2018)

In situ estimates of updraft velocities can also be achieved via releasing sensors or trackable objects into supercell updrafts from the storm's proximity. Chaff packets have been released from aircraft at thunderstorms' cloud bases and tracked with radar to estimate vertical velocities within supercells. Results from this approach have generally been consistent with those from in situ aircraft penetrations (Marwitz 1972, 1973). Radiosondes have also been used throughout the past 50 years, albeit infrequently, to estimate the vertical velocities in supercells (Barnes 1970; Davies-Jones 1974; Davies-Jones and Henderson 1975; Bluestein et al. 1988; Bluestein et al. 1989; Marshall et al. 1995; Markowski et al. 2018). From these radiosonde observations, the greatest reported w_{air} values were 49 m s⁻¹ (Bluestein et al. 1988) and 53 m s⁻¹ (Markowski et al. 2018), which occurred in Texas and Oklahoma, respectively.

Due to the challenges associated with in situ observations of updrafts, such as the hazardous sampling conditions and the difficulty of placing sensors directly within the updraft core, remotely-sensed observations have replaced in situ observations as the primary estimates of w_{air} in deep convection in recent decades. The most common method for estimating w_{air} with remote sensing utilizes data from multiple Doppler radars to determine the horizontal components of the wind, and then invokes the mass continuity equation to calculate the vertical component of the wind (e.g., Armijo 1969; Miller 1975; Kropfli and Miller 1976; Gal-Chen 1978). Multi-Doppler retrievals can provide vertical velocities over a relatively large domain and are often conveniently gridded to Cartesian coordinates. However, multi-Doppler estimates also have hard-to-characterize uncertainties due to their sensitivities to analysis specifications, such as how the data are filtered or interpolated (e.g., Nelson and Brown 1987; Miller and Fredrick 1998; Collis et al. 2010; Shapiro et al. 2010) or the temporal and spatial resolution of the data (e.g., Bousquet et al. 2008; Potvin et al. 2012; Oue et al. 2019; Dahl et al. 2019). Because of their

availability, these remotely-sensed observations have often been used to validate case study model simulations of deep convection in large field campaigns (Varble et al. 2014; Marinescu et al. 2016; Fan et al. 2017). These studies have shown that cloud-resolving models tend to produce stronger vertical velocities than their corresponding radar-derived estimates. However, the errors associated with multi-Doppler w_{air} are largely case-specific and depend on the radar scanning strategy, the type of convection and location of convection with respect to the radars (Oue et al. 2019). Therefore, it is still challenging to attribute the differences in updraft magnitudes from radar-based analyses and cloud-resolving models. In situ observations can thus assist in providing independent estimates of w_{air} .

In this study, we present GPS-radiosonde-based in situ observations and uncertainties of w_{air} within the updraft regions of two supercells. These observations were made during the Colorado State University Convective CLoud Outflows and UpDrafts Experiment ($C^3LOUD-Ex$) during 2016 and 2017 in the High Plains of Colorado, Wyoming, and Nebraska (van den Heever et al. 2020). Using the radiosonde data, along with radar observations within the $C^3LOUD-Ex$ domain, we (1) provide our best in situ estimates of w_{air} within the two supercell updrafts, (2) contextualize and compare these observations to other available w_{air} estimates for the two cases, and (3) offer insights for future efforts towards obtaining in situ observations within supercell updrafts.

2. C³LOUD-Ex Observations

a. Radiosondes

During C³LOUD-Ex, the iMet-1-ABxn radiosonde was used, which included a pressure, temperature and humidity sensor, as well as a GPS receiver (InterMet Systems 2016). The

radiosonde package was attached via a dereeler (30 m length) to a 200-g balloon that was filled with enough helium to reduce the helium tank's gauge pressure by approximately 3447 kPa (500 psi). For this study, the most essential radiosonde data were from the GPS receiver, which has a horizontal position accuracy of 10 m and an altitude accuracy of 15 m. GPS positions were received from the radiosonde at a rate of approximately 1 Hz and linearly interpolated to create a 1 Hz record.

Using the GPS altitude data, the vertical velocity of the radiosonde was estimated every second using a centered-in-time derivative:

$$109 w_{sonde} = \frac{\Delta z}{\Delta t} [Eq. 1]$$

where w_{sonde} is the representative vertical velocity of the radiosonde system over the time interval Δt , and Δz is the vertical distance traveled by the radiosonde during Δt . For this study, Δt is chosen to be 12 s, which for 10-60 m s⁻¹ updrafts equates to vertical distances of 120-720 m, comparable to current numerical model simulation grid spacings and/or observational grids. This Δt is chosen in order to reduce the periodic signals that were present in this dataset on the timescales of 12 s and less, as described in more detail in Appendix A. These periodic signals were likely associated with pendulum motions, which are theoretically estimated to have periods between 11-12 s for a dereeler length of 30 m. The periodic signals could also be associated with other self-induced balloon motions (e.g., Wang et al. 2009; Söder et al. 2019) that can occur on these small timescales. The error in this w_{sonde} , denoted $\epsilon_{w,sonde}$, was calculated using error propagation methods (e.g., Palmer 1912). Because the relative error in the GPS time measurement was several orders of magnitude smaller than the error in GPS position measurement, $\epsilon_{w,GPS}$ can be simplified to the following:

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$$\epsilon_{w,sonde} = |w_{sonde}| \left(\frac{\sqrt{2}\epsilon_z}{\Delta z}\right)$$
 [Eq. 2]

where ϵ_z is the error in the GPS altitude from the radiosonde (15 m). For a fixed $\Delta t = 12$ s and due to the linear relationship between w_{sonde} and Δz , $\epsilon_{w,sonde}$ is always \pm 1.8 m s⁻¹. For the cases presented in this study, each increase of 2 s in Δt , for Δt between 8 and 16 s, reduces the maximum vertical velocity observed by on average 0.1-0.5 m s⁻¹ due to smoothing and decreases the uncertainty by \pm 0.1-0.4 m s⁻¹. Therefore, the results are minimally impacted by the choice of Δt .

While w_{sonde} was directly observed by the radiosonde, the vertical velocity of the air that the radiosonde sampled (w_{air}) was desired. We decompose w_{sonde} into the following components: $w_{sonde} = w_{air} + w_{buoy} + w_{upd-drag} + w_{upd-hydro}$ [Eq. 3] where w_{buoy} is the vertical velocity arising from the buoyancy of the radiosonde system (balloon and radiosonde) in clear-sky, still-air conditions; $w_{upd-drag}$ is the vertical velocity associated with changes to the drag force on the radiosonde system within an updraft as compared to clear, still air; and $w_{upd-hydro}$ is the forcing from hydrometeors impacting or accumulating on the radiosonde system. Ultimately, by observing w_{sonde} , whose uncertainty ($\epsilon_{w,sonde}$) is known, and estimating w_{buoy} , $w_{upd-drag}$, $w_{upd-hydro}$, and their associated uncertainties ($\epsilon_{w,buoy}$, $\epsilon_{w,upd-drag}$, $\epsilon_{w,upd-hydro}$), an estimate of w_{air} and its uncertainty ($\epsilon_{w,air}$) can be determined.

Implicit in these definitions is that in clear-sky, still-air conditions w_{air} , $w_{upd-drag}$, and $w_{upd-hydro}$ are all ~0 m s⁻¹ and hence, $w_{sonde} = w_{buoy}$. Therefore, we estimated w_{buoy} from the w_{sonde} measurements obtained from thirteen radiosondes that were launched at the Colorado State University Foothills Campus in clear conditions with weak vertical motions throughout the troposphere. These radiosondes were launched during synoptic-scale ridges, which provided weak subsidence throughout the region. Seven launches took place overnight to minimize the influence of boundary layer vertical motions, as well as to eliminate the impacts of solar

radiation on the balloon, which could affect the buoyancy of the radiosonde system (Farley 2005). Vertical profiles of w_{buoy} for the clear-sky, still-air launches are shown in Figure 1a. The radiosonde descent rates (red), which occur after the radiosondes' balloons burst, vary with altitude and have a greater spread than the ascent rates (blue), which are approximately constant throughout the troposphere and lower stratosphere. Figure 1b shows a normalized histogram of the ascent rates from the rising radiosondes. The mean upward vertical velocity from these experiments is 4.8 m s⁻¹ (w_{buoy}), with 90% of the data falling within \pm 1.1 m s⁻¹, which we define here as $\epsilon_{w,buoy}$. We also estimated the w_{buoy} following the theoretical basis from Wang et al. (2009) and using a height-invariant drag coefficient of 0.5 for 7 clear air launches in which the free lift weights were directly measured prior to launch. The theoretical w_{buoy} varied with height, increasing from ~4.1-4.8 m s⁻¹ near the surface to ~5.0-6.0 m s⁻¹ at ~13 km AMSL. These theoretical values overlap with the height-invariant estimate of w_{buoy} obtained from observed w_{sonde} from the clear air launches (4.8 \pm 1.1 m s⁻¹).

It is unknown whether and how the drag force on the radiosonde system within supercell updrafts differs from that in clear air, and we therefore assume that the $w_{upd-drag}$ is 0 m s⁻¹ (i.e., no systematic shifts in the radiosonde-based w_{air} due to different drag forces within the updraft). Using the relationship between terminal velocity and the drag coefficient, however, we estimate that the uncertainty associated with variable drag forces on the radiosonde system within updraft conditions ($\epsilon_{w,upd-drag}$) is ± 1.6 m s⁻¹ (See Appendix B).

The forcing from hydrometeor impacts ($w_{upd-hydro}$) will typically be downward and can be caused by collisions with or accumulation of condensate mass (e.g., riming) on the radiosonde system. Because of the uncertainties in quantifying the presence and magnitude of these processes from the data available during C³LOUD-Ex, we did not attempt to estimate $w_{upd-hydro}$ or

its uncertainty in this study. Therefore, the radiosonde w_{air} is expected to be most accurate in scenarios where there is little to no impact from hydrometeors on the radiosonde system (i.e., outside of regions with hydrometeors). In such situations, the radiosonde w_{air} has an uncertainty ($\epsilon_{w,air}$) of ± 2.6 m s⁻¹, where $\epsilon_{w,air}$ is the summation in quadrature of $\epsilon_{w,sonde}$ (± 1.8 m s⁻¹), $\epsilon_{w,buoy}$ (± 1.1 m s⁻¹), and $\epsilon_{w,upd-drag}$ (± 1.6 m s⁻¹), following error propagation methods. In regions with hydrometeors, such as the cloudy regions of the supercell updraft, however, since $w_{upd-hydro}$ is negative for a rising balloon, the radiosonde w_{air} represents a lower bound on the actual w_{air} . It is important to note here that these estimates also assume that the balloon has not burst. Using the radiosonde accelerations and the radar observations (as described in Section 4), we estimated the times at which the balloons burst and made corresponding adjustments for those situations to provide a more realistic estimate of w_{air} .

b. Radars

Because the radiosondes provided localized measurements within the broad supercell updrafts, we used radar data to contextualize the in situ observations. Additionally, the radar data provided an independent estimate of w_{air} using dual-Doppler methods. Three radars were primarily utilized during C³LOUD-Ex: the CSU-CHILL radar (Brunkow et al. 2000), located in Greeley, CO; the Cheyenne, WY NEXRAD (KCYS); and the Denver, CO NEXRAD (KFTG). KCYS is located ~79 km to the north of CSU-CHILL, and CSU-CHILL is located ~74 km to the north of KFTG. Plan position indicator (PPI) scans from all radars, as well as additional range height indicator (RHI) scans from CSU-CHILL, provided detailed views of the storm structure and the relative position of the radiosonde within the storms. During C³LOUD-Ex, the NEXRAD radars (KCYS and KFTG) had prescribed volume coverage patterns (VCP212) that each lasted

~5 minutes, while the CSU-CHILL radar was manually operated and synchronized with the relevant NEXRAD radar during updraft-targeted radiosonde launches. Figure 2 shows an example of radar elevation angles for the NEXRAD and CSU-CHILL radars for one radar volume for the two cases examined in this study.

Reflectivity, velocity and some dual-polarization data from all three radars were used. These radar data were first quality-controlled using the dual-polarization data. Specifically, we excluded all radar gates where the standard deviation of the differential propagation phase was greater than 21 degrees over a range of 11 gates. We found that this threshold eliminated noise and ground clutter, while retaining more data near features of interest (e.g., the WER), which were otherwise eliminated when using correlation coefficient as a threshold. The radar velocity data were dealiased using the region-based method in the Python-ARM Radar Toolkit (Py-ART; Helmus and Collis 2016), and the storm motion for both cases was estimated for each 5-min radar volume scan using the Py-ART grid displacement algorithm on the radar reflectivity between 3 and 8 km AGL. These estimated storm motions were calculated for each radar volume and used for corrections related to storm translation in the dual-Doppler analyses, as well as for advecting the radar analyses in time for comparisons with the 1 Hz radiosonde data. Although these processing steps were largely automated, all quality-controlled and processed data were also manually checked.

Two analysis programs were then used to synthesize the radial velocity data and produce radar-based w_{air} estimates. These programs were the Custom Editing and Display of Reduced Information in Cartesian space (CEDRIC; Miller and Fredrick 1998) and the Spline Analysis at Mesoscale Utilizing Radar and Aircraft Instrumentation (SAMURAI; Bell et al. 2012). While these programs both solve the basic radar equations, CEDRIC uses column-by-column vertical

integration of the mass continuity equation to produce local solutions for each vertical column, while SAMURAI uses a 3D-variational approach (Gao et al. 1999) and produces a global solution for the entire analysis domain via a cost minimization function. The 3D-variational approach has been shown to produce better vertical velocity solutions for a supercell case than other methods (Potvin et al. 2012). These analyses were completed on 1-km and 500-m Cartesian grids for the 26 May 2017 and 17 July 2016 cases, respectively, due to the relative locations of each storm with respect to the radars as shown in the following section. The top boundaries in the analyses were set to 17 km AMSL (5-6 km above the tropopause) and the vertical velocities were set to 0 at the top boundary in SAMURAI and at half a vertical grid level above the highest level where divergence was calculated in each column in CEDRIC. For the CEDRIC analyses shown here, the variational vertical integration method was used, whereby downward integration was first completed, residual errors were spread throughout the column in an iterative manner and lastly, variationally adjusted integration was applied (e.g., W_{var} in Dolan and Rutledge 2010). A linear, least-squares two-dimensional filter was also used on the horizontal winds in the CEDRIC analyses (Miller and Fredrick 1998). Low-pass filters with approximate scales of 4-km and 2-km for the 1-km and 500-m Cartesian grids, respectively, were applied in the SAMURAI analyses (Ooyama 2002, Purser et al. 2003).

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3. C³LOUD-Ex Cases

During C³LOUD-Ex, there were 7 cases in which the updrafts of supercell storms were successfully sampled with radiosondes (van den Heever et al. 2020). In this study, we focus on the two cases that had successful radiosonde sampling of updrafts within the regions where dual-

Doppler estimates of w_{air} could also be made. These occurred on 26 May 2017 and 17 July 2016 and are briefly described in the following two sections and summarized in Figure 3.

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a. 26 May 2017 Case Study

At 18:15 UTC, an environmental sounding (Fig. 3b) was launched at 39.72 °N, 104.22 °W and showed 0-6 km shear of 26 m s⁻¹, mixed-layer (0-90 hPa AGL) convective available potential energy (MLCAPE) of 491 J kg⁻¹, and surface-based CAPE of 1882 J kg⁻¹. By 20:00 UTC (UTC = local time + 6 hours), terrain-induced scattered convection was moving eastwards over the Denver metropolitan region. The destabilized boundary layer and favorable environmental conditions resulted in the development of an isolated supercell by 22:00 UTC, located within the dual-Doppler analysis region for the CSU-CHILL and KFTG radars (Fig. 3a). At 21:58 UTC, a radiosonde (2017-1) was launched and sampled the updraft of the developing supercell, while 1.5 inch (3.8 cm) diameter hail was reported at the surface nearby (NCEI 2017). Around 22:00 UTC, the storm propagation slowed and took a rightward turn towards the eastsoutheast. Over the next several hours, many instances of hail with diameters of 1-1.5 inches (2.5-3.8 cm) were reported at the ground along the storm's path, as were 2 weak tornadoes (NCEI 2017). Two additional radiosondes (2017-2 and 2017-3) sampled the supercell updraft between 22:00 and 24:00 UTC. This long-lived supercell continued into Kansas, outside of the C³LOUD-Ex domain, and subsequently became part of a mesoscale convective system.

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b. 17 July 2016 Case Study

 $^{\rm 1}$ The CAPE calculations in this study are based on Bryan (2008).

On 17 July 2016 at ~20:30 UTC, convection that had initiated over the high terrain of southern Wyoming moved eastward onto the high plains to the northwest of Cheyenne, Wyoming, where it quickly organized into a supercell and subsequently turned towards the southeast (Fig. 3c). Earlier in the day, between 18:00 and 19:00 UTC, three radiosondes were launched (at 40.67 °N, 104.33 °W; 41.22 °N, 104.35 °W; and 41.24 °N, 103.70 °W) to better capture the environment ahead of this storm. These observations (Fig. 3d) indicate MLCAPE of ~950-1200 J kg⁻¹ and 0-6 km shear of 21-25 m s⁻¹. This supercell propagated southeastward across the C3LOUD-Ex domain, including through the region where dual-Doppler analyses could be conducted using the CSU-CHILL and KCYS radars. This storm had more intense radar reflectivity than did the 2017 case, and there were several reports of 2.0-inch (5.1-cm) diameter hail as well as a few baseball-sized hailstones (diameters of ~7.5 cm; NCEI 2016). As the supercell propagated southeastward, two radiosondes were launched into the supercell's main updraft region (Fig. 3c). The first, 2016-1, was located within the dual-Doppler analysis region, while the second, 2016-2, was just outside the dual-Doppler lobes in a more unstable environment. By 01:30 UTC on 18 July 2016, the storm began to lose many of its supercellular characteristics, and it dissipated by 03:00 UTC.

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We note here that both of these High Plains supercells experienced environments with substantial vertical wind shear (0-6 km; ~21-26 m s⁻¹) and moderate MLCAPE (~1000-1600 J kg⁻¹). These environments had bulk Richardson numbers of ~10-15, well within the range favorable for supercells (Weisman and Klemp 1982), although the MLCAPE values are on the lower end of those conditions supporting weakly-tornadic and non-tornadic supercells within the broader United States (Thompson et al. 2003). Therefore, these C³LOUD-Ex observations of *wair*

will likely be lower than similar observations of supercells in more unstable air masses, such as those present in the U.S. southern Great Plains.

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4. Radiosonde-derived updraft wair

The w_{air} estimated from the 5 radiosondes that sampled the two supercells' updrafts are shown in Figure 4, which for simplicity's sake only depicts w_{air} from when the radiosonde was launched to when the radiosonde reached its maximum altitude. The horizontal wind speed and direction were also calculated from the raw GPS data every second, using the same Δt of 12s. These radiosonde data represent point locations within the large supercell updrafts. Despite the radar's inability to observe the finer scale motions observed by the radiosondes, the radar data were useful for determining the position of the radiosonde within the updraft and elucidating whether each radiosonde was in the vicinity of the strongest w_{air} within these storms. The radiosondes took many different trajectories throughout the supercells. Only one of these five radiosondes (2017-2) continued to rise into the stratosphere after sampling the supercell updraft. The other radiosonde systems likely experienced conditions within the updraft that robbed them of their positive buoyancy (e.g., radiosonde balloon bursting or significant riming). In order to identify these events, the radiosonde-derived accelerations were calculated from the difference in the 1 Hz w_{air} data and were examined for the entirety of the radiosondes' data transmissions (Fig. 5). A 5-second moving average was applied to the calculated acceleration to eliminate noise but still capture significant events. The most intense negative accelerations were assumed to be associated with the radiosonde balloon bursting, whereby w_{buoy} instantaneously changed from approximately +4.8 m s⁻¹ to anywhere between -15 to -25 m s⁻¹, depending on the radiosonde's tropospheric altitude (Fig. 1a). It is possible that such intense negative accelerations could also

be a result of significant icing and hydrometeor collisions with the balloon, although these effects are unquantifiable in our dataset. The most intense negative accelerations are highlighted in yellow in Figure 5 and had values between -1.4 and -4.3 m s⁻². These values were similar to those associated with the radiosonde balloon bursts during the clear-sky, still-air launches, which all occurred above 16 km AMSL and ranged from -2.2 to -4.8 m s⁻² (not shown). For radiosondes 2017-2 and 2016-1, the radiosondes' balloons did not burst until right before their final descents to the surface. However, for radiosondes 2017-1 and 2016-2, it appears that the balloon burst within the radiosonde's initial ascent through the updraft, based on the assumption that the most negative accelerations represent balloon bursts. While the likelihood of this relationship has yet to be established, radar data (shown in the following sections) suggest that the radiosondes 2017-1 and 2016-2 were entering regions of large hail within intense updrafts during their most negative accelerations, conditions that can cause a radiosonde balloon to burst. If the balloons had not burst, we would have expected these radiosondes to eventually exit the storm and rise into the stratosphere. Therefore, for radiosondes 2017-1 and 2016-2, adjustments were made to the radiosonde-derived w_{air} after the assumed balloon burst event (Fig. 4, smaller dots), taking into account the altitude-dependent, mean terminal velocities of the descending radiosonde system (Fig. 1a). For radiosonde 2017-3, communication was lost with the radiosonde during its ascent within the updraft before any significant negative accelerations occurred, and therefore, no adjustments were necessary.

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Before the adjustments described above, the maximum w_{air} values measured by the radiosondes for the 2017 and 2016 cases were 36.2 and 25.5 m s⁻¹, respectively. After adjusting for the balloon burst assumption for the 2017-1 and 2016-2 radiosondes, the respective maximum radiosonde w_{air} values were 45.8 and 49.9 m s⁻¹. Here, it is important to emphasize

that there is larger uncertainty in w_{buoy} after the balloon burst, in part due to the larger spread of descent rates that are used for the adjustments and which are based on the clear air radiosondes after their balloons burst (Fig. 1a). However, making this adjustment provides a more realistic estimate of w_{air} , assuming the radiosonde balloon does burst. Additional testing would be needed to quantify the uncertainties for these adjusted w_{air} estimates. In the next sections, we present the radiosonde w_{air} for each launch in the context of the radar data.

a. 2017 Case

Radiosonde 2017-1 was launched at 21:58 UTC, shortly after the supercell formed and within the dual-Doppler analysis region for the CSU-CHILL and KFTG radars. Figure 6 depicts the radiosonde w_{air} along with two snapshots of the radiosonde position within the storm based on the radar reflectivity and dual-Doppler-derived w_{air} . Based on the radiosonde humidity data, the radiosonde entered cloud around 2.7 km AMSL, at which point w_{air} , the updraft vertical velocity, was 5.5 m s⁻¹. This corresponds to an average rate of acceleration from the ground level to cloud base of 0.034 m s⁻². The radiosonde continued to accelerate within the cloudy updraft through ~7.5 km AMSL at an average rate of 0.116 m s⁻², more than triple the rate below cloud base, and the horizontal winds decreased from ~10 m s⁻¹ to ~1 m s⁻¹ and shifted from southerly to northerly (Fig. 4b-c).

During this time period, the radiosonde was located within the main updraft, along the western part of the weak echo region. At 7.5 km AMSL (Fig. 6b-g), the radiosonde decelerated for ~15-20 s as it entered a region of higher reflectivity (>50 dBZ) and low correlation coefficients (<0.9, not shown), suggesting large hail (e.g., Balakrishnan and Zrnic 1990; Rhyzkov et al. 2013). Although the dual-Doppler analyses do not resolve the winds on the scales

observed by the radiosonde, the fact that both dual-Doppler analyses (Fig. 6e,g) depict increasing w_{air} with height (which would suggest positive balloon acceleration as opposed to deceleration) supports our hypothesis that the balloon burst. As such, above 7.5 km AMSL, adjustments were made to the w_{air} estimates using a w_{buoy} corresponding to a burst radiosonde balloon, as described in the prior section. At 9.7 km AMSL (Fig. 6h-m), the w_{air} after adjustments reached its peak value (45.8 m s⁻¹). At this time, the radiosonde was within the primary updraft region but was nevertheless located ~5 km to the southwest of the most intense radar-derived updrafts (Fig. 6j,l), suggesting that the maximum w_{air} in this storm was likely even higher than that estimated from the radiosonde. We note that the adjusted radiosonde w_{air} values are more intense than those from the radar analyses, and the w_{air} estimates from the different observing platforms are compared in Section 5a. The radiosonde reached its maximum altitude of 10.6 km AMSL after experiencing north-northwesterly winds for 2-3 min, which advected the radiosonde to the southern periphery of the updraft, where the w_{air} was no longer strong enough to suspend the radiosonde system.

Approximately 1 hour later (22:51 UTC), another radiosonde (2017-2) was launched into the supercell updraft. Although the supercell was no longer within the region where dual-Doppler estimates could be made, both radar RHIs (not shown) and PPIs were used to contextualize the radiosonde measurements. Figure 7 shows PPI snapshots throughout the radiosonde trajectory at times when the radiosonde location was simultaneously sampled by one of the radars. The 2017-2 radiosonde was launched to the southwest of the WER (Fig. 7b), was advected northwards in the inflow, and observed w_{air} of ~14 m s⁻¹ before entering the cloud at 3.7 km AMSL, which was above cloud base. A maximum w_{air} of 36.2 m s⁻¹ was obtained at approximately 10.4 km AMSL (Fig. 7e). Despite observing strong w_{air} throughout its trajectory,

the radiosonde was consistently located ~5-10 km to the southwest of where the strongest w_{air} was likely located: the WER in the lower and middle troposphere (Fig. 7c,d) and the higher reflectivity regions in the upper troposphere (Fig. 7e). After reaching the top of the storm, the radiosonde underwent negative acceleration and sampled a minimum w_{air} of -26.1 m s⁻¹, which was likely associated with strong downdrafts south of the main updraft (Fig. 7f). Unlike the 2017-1 radiosonde, 2017-2 eventually exited the storm (Fig. 7g) and rose to an altitude of 22.2 km AMSL before the radiosonde balloon burst.

At 23:59 UTC, a third radiosonde (2017-3; Fig. 8) was launched and subsequently sampled the WER in the middle troposphere (Fig. 8b,c). This radiosonde experienced the strongest vertical velocities between the surface and 6.8 km AMSL of all three radiosondes from this case, accelerating at an average rate of 0.113 m s⁻² from 4.3 m s⁻¹ at 2 km AMSL to a maximum w_{air} of 31.1 m s⁻¹ at 7.1 km AMSL. Unfortunately, the thermodynamic sensors were compromised during the radiosonde launch, and thus it is unclear at exactly which point the radiosonde entered cloudy conditions. Above 7.1 km AMSL, the radiosonde began to decelerate and likely encountered rain and/or hail (Fig. 8a,d); communication with the radiosonde was lost at 10.8 km AMSL.

b. 2016 Case

Similar analyses were conducted for radiosondes 2016-1 and 2016-2 for the isolated supercell that occurred on 17 July 2016. Because the supercell passed closer to the radar network (Fig. 3c), the dual-Doppler analyses were conducted with 500 m grid spacing, which allowed for a more detailed structure in the w_{air} values, although the analyses were still unable to resolve the finer-scale motions observed by the radiosondes.

At 22:24 UTC, the 2016-1 radiosonde (Figs. 9-10) was launched on the southern side of
the supercell, shortly after the cold pool associated with the rear flank downdraft passed the
launch location, resulting in negative-to-neutral w_{air} and northwesterly winds near the surface
(Fig. 9a; Fig. 5). A radiosonde-based w_{air} of ~23 m s ⁻¹ was observed twice during the
radiosonde's ascent through the storm (at 6.8 km and 9.1 km AMSL; Fig. 9). In both instances,
the radiosonde was in the extreme southwest edge of the updraft region, and ~10 km to the west
of the WER (Fig. 9b-c; Fig. 9h-i). The radiosonde continued to rise above 12 km AMSL and then
underwent a 2.5 km descent, during which it observed a minimum w_{air} of -26.8 m s ⁻¹ (Fig. 10b-
g). This radiosonde, however, experienced its most intense negative acceleration immediately
before the radiosonde's final descent to the surface (Fig. 5d), and therefore, we propose that this
first radiosonde descent was associated with nearby, strong upper-level downdrafts that were
diagnosed by both the SAMURAI analysis (Fig. 10f-g) and, to a lesser extent, the CEDRIC
analysis (Fig. 10d-e) rather than with the balloon bursting. The radiosonde then experienced
several vertical oscillations, ascending and descending 3 times around 10-11 km AMSL and ~15
km to the southeast of the main updraft (Fig. 10h-m). These oscillations were likely associated
with gravity waves in the anvil, which are evident in the CEDRIC analyses (Fig. 10j-k), but less
so in the SAMURAI analyses (Fig. 10l-m) due to the filtering scales and different approaches
used (Section 2b). The relatively weak vertical motions in the anvil (Fig. 10j-m) would not have
been strong enough to suspend the radiosonde had the balloon burst, providing further evidence
that the balloon did not burst until right before the radiosonde's final descent to the surface.
At 23:41 UTC, radiosonde 2016-2 was launched to the south of the WER (Fig. 11b) and
was likely closer to the regions with the most intense vertical motions than was radiosonde 2016-
1 This radiosonde experienced strong southerly winds, particularly between 6 and 8 km AMSI.

(Fig. 4b-c) that advected it towards the storm's updraft. At 8 km AMSL, however, the radiosonde experienced its most intense negative acceleration (Fig. 11a,c, Fig. 5e) and a significant decrease in horizontal wind speeds (Fig. 4b), while the radiosonde was entering a region to the north with high reflectivity (> 50 dBZ) and correlation coefficients < 0.94, which suggests large hail. Based on this evidence, we suspect that the balloon burst at this time right before being entrained into the storm's intense updraft. Therefore, adjustments were made to w_{air} to account for this balloon burst assumption. However, we acknowledge that this 2016-2 balloon burst assumption is more uncertain than that for the 2017-1 balloon. The radiosonde measured a maximum estimated w_{air} of 49.9 m s⁻¹ at 10.3 km AMSL (Fig. 11a). Shortly after this maximum value was reached, the radiosonde was located within the region of maximum reflectivity at 12.1 km AMSL (Fig. 11d). This suggests that the radiosonde was near some of the storm's most intense vertical motions, which were able to loft large hydrometeors to these near-tropopause heights. Considering the assumptions and adjustments for balloon bursting, 49.9 m s⁻¹ was the strongest vertical velocity observed by a radiosonde from these two C³LOUD-Ex cases. This result is consistent with the fact that this radiosonde was launched in the most unstable (i.e., highest CAPE) environment of all the radiosondes (Fig. 3c; Table 1), as will be discussed in Section 5b. It is important to restate that none of these estimates considers the impacts of hydrometeors, which would lead to both an underestimation of and an additional uncertainty in the w_{air} values presented.

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- 5. Comparisons of radiosonde w_{air} to other platforms
- a. Comparisons with dual-Doppler estimates

In addition to contextualizing the radiosonde observations, the radar data also provide an independent estimate of w_{air} for radiosondes 2017-1 and 2016-1. It is important to note the differences in the features that the two types of observing systems can resolve. The values in the dual-Doppler analyses represent the *average* vertical velocity over a cube with side lengths of 1 km (500 m) for the 2017 (2016) case using data collected over a 5-minute interval. The radiosonde values, however, represent averages along a slantwise path corresponding to the radiosonde trajectory over the course of the 12 s averaging period (e.g., horizontal and vertical distances generally between 150 and 700 m). Such differences need to be considered when comparing these estimates of vertical velocity obtained using these different platforms.

A comparison of radiosonde w_{alir} with the dual-Doppler w_{alir} from SAMURAI and CEDRIC is shown in Figure 12. The dual-Doppler analyses for each radar volume were calculated at the volume-scan midpoint time and were advected in time using the calculated storm motion for each radar volume to create a 4D dataset. These 4D data were interpolated in time and space to the same position as the radiosonde for this comparison. To account for shifts in position within the dual-Doppler analyses that may be due to small advection errors, we also show the range of values in the surrounding grid boxes that are 1 km from the radiosonde location in the horizontal plane. This spread does not, however, represent any underlying uncertainty in the radar dual-Doppler analyses, which can come from a variety of sources as described in the introduction. In particular, the distance of these $C^3LOUD-Ex$ storms from the radars, combined with the fixed NEXRAD radar scanning patterns, as well as the homogeneous advection corrections (e.g. Shapiro et al. 2010) could both produce significant sources of error. However, these errors can only be quantified from additional observation system simulation experiments (OSSEs; e.g., Potvin et al. 2012; Oue et al. 2019; Dahl et al. 2019).

Comparisons cannot be made below 3.7 km AMSL (Fig. 12a) and 6.0 km AMSL (Fig. 12b) for the 2017 and 2016 cases, respectively, due to the lack of quality radar data at the radiosonde locations. This demonstrates one benefit of the radiosonde observations, namely their ability to sample vertical motions where radars only observe very low signal-to-noise ratios, such as below cloud base and along cloud edges. Based on the C^3LOUD -Ex radiosonde observations, w_{air} can approach 20 m s⁻¹ in these regions.

Both dual-Doppler analyses show consistent trends and similar magnitudes of w_{air} . In both cases and for both dual-Doppler analyses, at the locations where the radiosondes observe the strongest w_{air} , the dual-Doppler w_{air} values was generally 15-20 m s⁻¹ less than those derived from the radiosondes. For radiosonde 2017-1 (Fig. 12a), right before it is assumed that the balloon burst at 7.5 km AMSL, the difference between the radiosonde w_{air} and those of both dual-Doppler analyses was ~15-20 m s⁻¹. For radiosonde 2016-1 (Fig. 12b), similar differences were present at 6.8 and 9.1 km AMSL. This dual-Doppler underestimation of w_{air} as compared to the most intense radiosonde wair was at least partly due to the radiosonde capturing localized features that were unable to be resolved by the resolution of these radar analyses. However, without a detailed error estimation of the dual-Doppler syntheses obtained from OSSEs for these cases, we are unable to quantify how much of the differences are due to errors associated with the C³LOUD-Ex radar network and scanning patterns (e.g., Oue et al. 2019) versus systematic differences in the observed quantities. Regardless, this comparison does demonstrate that a comprehensive analysis of w_{air} would benefit from in situ measurements that can better capture highly localized conditions.

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b. Comparisons with parcel theory

Parcel theory can also be used to estimate the theoretical maximum possible vertical velocity due to its relationship with CAPE (e.g., Weisman and Klemp, 1984):

 $490 w_{MLCAPE} = \sqrt{2 \cdot MLCAPE} [Eq. 4]$

MLCAPE is chosen, as compared to other CAPE variants (e.g., surface-based or most-unstable), because it more realistically represents the air entering deep convective updrafts. The expression shown in Eq. 4 assumes that vertical accelerations are only forced by buoyancy and does not account for the negative impacts from condensate loading and entrainment. Eq. 4 also does not consider the impacts of perturbation pressure gradients, which have been shown to decelerate updrafts within the upper levels of supercells where the maximum vertical velocities are achieved (Peters et al. 2019). Therefore, Eq. 4 likely overestimates the maximum vertical velocities in supercell updrafts.

To assess Eq. 4 with respect to the C³LOUD-Ex observations, MLCAPE (0-90 hPa AGL) is calculated for each radiosonde launch. These calculations assume pseudoadiabatic ascent and account for the latent heating associated with freezing above the 0 °C level by assuming that ice fraction linearly increases from 0 °C to -40 °C. While the sub-cloud-layer radiosonde data sampled by the updraft radiosondes are generally representative of the environmental air entering the supercell updraft, the data within the cloudy updraft are no longer representative of the environmental conditions needed to estimate MLCAPE. Therefore, the thermodynamic data from lowest levels of the updraft soundings were merged with data from the middle and upper levels of the environmental soundings (Fig 3b,d). This concatenation occurred at the altitude where the temperature profiles first overlapped for each pair of soundings, near the inversion of the environmental sounding between 700 and 800 hPa. In cases where the radiosonde was launched

in a cold pool or the thermodynamic data were not available (radiosondes 2016-1, 2017-1, and 2017-3), the closest, representative radiosonde launch in time and space was used as a better estimate of the inflow air for that radiosonde launch, since we are interested in estimating the theoretical maximum vertical velocities.

Overall, the w_{MLCAPE} values calculated via parcel theory were larger than the w_{air} values observed by the radiosondes (Table 1). Further, these results highlight the variability of w_{air} within the primary supercell updraft. The ratio of w_{air} to w_{MLCAPE} ranges from 42% to 89%, largely due to the variability in the positions sampled within the supercell updrafts. When the balloon burst assumption is not considered, the ratios for radiosondes 2017-1 and 2016-2 fall from 89% and 74% to 67% and 38%, respectively. Assuming the correct identification and adjustments for balloon bursts, the radiosonde with the smallest ratio (42%, 2016-1) sampled the extreme western edge of the primary updraft, ~10 km from the WER (Fig. 9). The radiosonde with the largest ratio (89%, 2017-1) sampled close to where the most intense vertical motions were likely located (Fig. 6). While the maximum vertical velocities estimated from these radiosonde data do not reach their theoretical maxima, as predicted by Eq. 4, a larger sample of observations, especially those similar to radiosonde 2017-1 that sampled near the most intense w_{air} , is needed to better observationally assess the relationship shown in Eq. 4.

6. Implications for future in situ observations of w_{air} within storms

This study has shown that GPS sensors aboard radiosondes can provide useful in situ observations of w_{air} within storms, especially when used in conjunction with radar data. Understanding the position within the updraft being sampled by the radiosonde provided valuable context for interpreting the radiosonde observations. Particularly with GPS radiosondes

that can directly transmit their locations while sampling, coordinated scanning of radars through the use of PPIs and RHIs to the exact positions of airborne radiosondes should be considered for future field campaigns. For example, using these collocated radar and radiosonde observations, we demonstrated that most of the radiosonde measurements were likely several km away from the strongest w_{air} in these two supercell updrafts. Obtaining large samples of in situ observations in the locations of strongest w_{air} within storms continues to be challenge, but forgoing cost constraints, this sampling difficulty can be alleviated by launching a high number of GPS sensors into storms (e.g., Markowski et al. 2018) so as to increase the probability of sampling the most intense vertical motions. This would also simultaneously improve the spatial coverage of these in situ measurements.

While several of the uncertainties in the radiosonde-based w_{air} were quantified in this study, we did not quantify the uncertainty associated with hydrometeor collisions and collection on the radiosonde system. Innovative techniques and technologies to minimize or quantify these hydrometeor impacts would improve radiosonde observations within cloud systems. For example, cameras have been placed on radiosondes to assess icing impacts on in situ observations within winter storms (Waugh and Schuur 2018), and similar strategies could potentially be used to observe the possible accumulation of hydrometeors on the radiosonde system within updrafts. Furthermore, we analyzed balloon accelerations and assumed, with contextual support, that the radiosonde balloon burst when it experienced its most negative accelerations, in order to obtain a better estimate of w_{air} . However, this assumption was more uncertain for radiosonde 2016-2 due to the less clear trajectory and more turbulent conditions, as compared with radiosonde 2017-1. Additional sensors could be introduced to the radiosonde system to assist in assessing balloon burst events, which would reduce these uncertainties.

7. Conclusions

One of the goals of the C³LOUD-Ex field campaign was to obtain in situ observations of the vertical velocities of supercell updrafts (w_{air}) with targeted radiosonde launches. In situ observations of supercell vertical velocities have been limited, despite their importance for understanding physical processes within supercells and for verifying simulations as well as other observational platforms with difficult-to-characterize uncertainties. In this study, we present observations of w_{air} from two isolated supercell cases observed during C³LOUD-Ex, which occurred in the High Plains of Colorado, Wyoming, and Nebraska. Radiosonde w_{air} estimates were based on GPS data and were calculated with an uncertainty of \pm 2.6 m s⁻¹, which considered uncertainties associated with the GPS measurements themselves, the helium balloon buoyancy, and varying drag forces. These estimates, however, did not consider hydrometeor impacts on the radiosonde systems which could be significant and would lead to an underestimation of the w_{air} presented in this study.

In two of the five updraft radiosonde launches assessed in this study, we inferred that the radiosonde balloon burst while within the updraft, based on the extrema in the radiosonde negative accelerations. In these instances, we adjusted the w_{air} estimates to account for the loss of buoyancy associated with balloon bursting. Before these adjustments, the maximum radiosonde w_{air} was 36.2 m s⁻¹ at an altitude of 10.4 km AMSL during the 2017 case. After these adjustments, the maximum w_{air} that was observed was 49.9 m s⁻¹ at an altitude of 10.3 km AMSL during the 2016 case, which occurred in the most unstable environment. At the lower and middle tropospheric levels, radiosonde 2017-3 captured the greatest w_{air} and was located within the WER, reaching a maximum value of 31.1 m s⁻¹ at 7.1 km AMSL. In most of the observations

presented, the radar data suggested that the radiosondes were several km away from the strongest w_{air} within the supercell updraft. This fact, along with the potential impacts of hydrometeors on the radiosonde systems, suggests that the maximum w_{air} in these two supercells was likely even larger than the values reported here.

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The C³LOUD-Ex radiosonde observations were also compared with other methods of obtaining w_{air} . One radiosonde in each of the two supercell cases sampled the updraft within the regions where dual-Doppler analyses could be performed, allowing for an independent measure of w_{air} . For the locations where the radiosondes observed the greatest w_{air} , the dual-Doppler w_{air} values were generally 15-20 m s⁻¹ less than the radiosonde estimated w_{air} values. This was at least partly due to the different scales being observed by these two platforms, although it was difficult to fully quantify these differences without a detailed assessment of the dual-Doppler errors, such as may be obtained through the use of OSSEs, and which is left for future work. However, these comparisons did demonstrate that radiosondes provide complementary data to multi-Doppler analyses in terms of their ability to sample regions with low signal-to-noise ratios and to provide localized, high-resolution observations, both of which can be challenging in multi-Doppler analyses. When the balloon burst correction was included, the maximum radiosonde-based w_{air} values were 42-89% of the theoretical maximum w_{air} from parcel theory. The variability in these comparisons was primarily due to the locations within the broad supercell updrafts that were sampled by the radiosondes, which were ascertained using collocated radar data.

Some of the challenges associated with making radiosonde observations of updrafts were highlighted here, and additional ideas on how these challenges can be surmounted were provided. There continues to be large uncertainty in the vertical velocities within deep

convection, which are important for understanding many atmospheric processes and improving models. In situ observations of w_{air} can complement remotely-sensed estimates both by providing both an independent measure of w_{air} for comparison and by observing finer-scale motions that often cannot be resolved using remote sensing. As such, despite their relative scarcity, in situ observations of w_{air} can contribute to a more comprehensive understanding of storm vertical motions and hence should be considered for future field campaigns.

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Appendix A: Power Spectra Analysis of Radiosonde Velocity Data

In order to determine the choice of Δt , power spectra were computed for all the clear air and updraft radiosonde launches presented in this manuscript. The vertical wind speeds (*wair*), horizontal wind speed (h_{spd}) , and horizontal wind direction (h_{dir}) were first calculated with a Δt of 2 s, using the GPS data from the position 1 s before and after the current position. Power spectra analyses, following the methodology in Marinescu et al. (2019), were then conducted on these data. To summarize this methodology, these 1 Hz data were broken down into data chunks that were 180 s long and accurately resolved periodic signals from 2 to 90 s. This data chunking resulted in anywhere from 5 to 49 data chunks for each radiosonde launch, and the power spectra from these data chunks were then averaged together to create a better statistical representation of the periodic signals within each launch's data (thin lines in Fig. A1). The power spectra from each radiosonde launch were also combined for all the clear air, updraft and all launches, respectively, and averaged (thick lines in Fig. A1). Red-noise power spectra were estimated using the average lag-1 autocorrelations from these data groups, as a reference for these data without any periodic signals (Gilman et al. 1963). A periodic signal in the observed data is interpreted to be present if the data has more power than the red-noise power spectra for that

period. From these analyses, it is clear that periodic signals are present in this data on time scales of ~12 s and less in all the wind data. These results are consistent with the theoretical calculation of the ~11-12s period of a pendulum with a 30-m string, which represents the length of the radiosonde dereeler using during C^3LOUD -Ex. Interestingly, the updraft launches (red, thick line) have more consistent periodic signals with periods between 6.0-6.5 s in the wind speeds, while the clear air launches have more consistent signals between 9-12 s, 5 s, and 3.3 s, suggesting slight differences in the radiosondes' periodic motions between these two conditions. Overall, these power spectra guided the choice of using a Δt of 12 s, which substantially reduced the contribution of these periodic signals with time scales of 12 s and less in the updraft w_{air} calculations, while still allowing for finer-scale observations and error propagation analyses.

Appendix B: Analysis of $\epsilon_{w,upd-drag}$

 $\epsilon_{w,upd-drag}$ is the uncertainty in the w_{air} estimate arising from changes in the drag force on the radiosonde system within an updraft as compared to still air conditions. Because radiosonde systems typically reach their terminal velocity within a couple of seconds and are often close to terminal-velocity balance, we can use the formula for the terminal velocity and its dependence on the drag coefficient (C_D) to estimate the uncertainty.

The terminal velocity (v_T) of the radiosonde system can be determined as follows (following, e.g., Wang et al. 2009; Gallice et al. 2011):

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$$v_T = \sqrt{\frac{2g(net_free_lift)}{\rho C_D A}}$$
 [Eq. A1]

In Eq. A1, net free lift (units of kg), when multiplied by acceleration due to gravity $g \sim 9.81$ m s⁻², is the upward buoyant force acting on the radiosonde system. Net free lift is calculated as the difference of two quantities: (1) the mass measured when the helium-filled balloon is attached to

a spring scale (typical value of 1.03 kg; range from 0.86 kg to 1.40 kg); and (2) the combined mass of the radiosonde and dereeler attached to the balloon (0.24 kg). These measurements were taken during the clear-sky, still-air launches described in Section 2a. The other variables in Eq. A1 include the ambient air density ρ , the drag coefficient C_D , and balloon cross-sectional area A. The helium inside the balloon is assumed to expand adiabatically as the balloon rises. The initial A of the balloon is approximately 1.33 m², obtained from the clear-sky, still-air launches. Based on prior laboratory studies using perfect spheres (Achenbach 1972; Son et al. 2010) and on radiosonde observations during relatively calm, nighttime conditions (Gallice et al. 2011), drag coefficients for tropospheric conditions generally fall between 0.2 and 0.5. The drag coefficient within a supercell updraft may fall outside of this range, but we have no way of knowing whether this is the case due to the lack of observations. Using the known range of tropospheric drag coefficients from relatively calm conditions and using a range of tropospheric air densities, we can estimate the uncertainty of v_T , and thus w_{air} , due to variations in C_D based on Equation A1 (Fig. A2). The range of v_T as a function of air density (gold line) is at most 3.1 m s⁻¹, which occurs at the lowest density included (0.3 kg m⁻³, representative of the upper troposphere). Therefore, we estimate that $\epsilon_{w,upd-drag}$ is \pm 1.6 m s⁻¹, which is half of the maximum range (3.1 $m s^{-1}$).

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Data Accessibility

The radar and radiosonde data analyzed in this manuscript are all available upon request. The HRRR data were obtained from an archive of the High Resolution Rapid Refresh model (doi:10.7278/S5JQ0Z5B).

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Table 1: 0-90 hPa AGL MLCAPE, the theoretical maximum w_{MLCAPE} based on Eq. 4, and comparisons with the maximum radiosonde w_{air} for each radiosonde launch. For instances where the assumption of a balloon burst was used, two values are shown. The first represents the value including the balloon burse assumption, while the second, in parenthesis, represents the value without adjusting for a balloon burst.

Radiosonde	MLCAPE (J kg ⁻¹)	WMLCAPE (m s ⁻¹)	Maximum radiosonde w_{air} (m s ⁻¹)	Ratio of w_{air} to w_{MLCAPE} , as a percentage
2017-1	1313	51.2	45.8 (34.4)	89.4% (67.2%)
2017-2	1172	48.4	36.2	74.9%
2017-3	952	43.6	31.1	71.4%
2016-1	1510	55.6	23.4	42.2%
2016-2	2305	67.9	49.9 (25.5)	73.5% (37.6%)

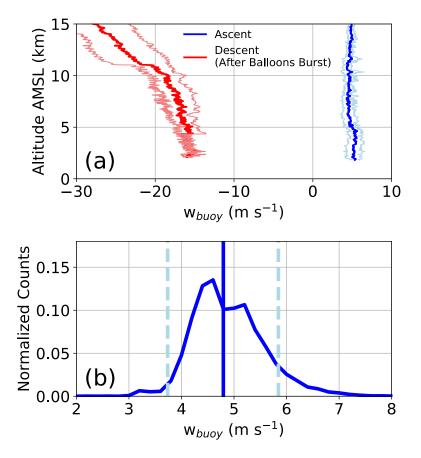


Figure 1: (a) Mean w_{buoy} during the clear, still air launches from ascending radiosondes (blue) and from descending radiosondes, after the balloons burst (red). Light blue and red lines represent 1 standard deviation from the mean. Data are not available for most descending radiosondes below 4.5 km AMSL. (b) Normalized histogram counts from all w_{buoy} from ascending radiosondes shown in (a), with the vertical, solid line representing the mean value (4.8 m s⁻¹) and dashed lines representing \pm 1.06 m s⁻¹ from the mean, between which 90% of the data falls. The bin width is 0.2 m s⁻¹.

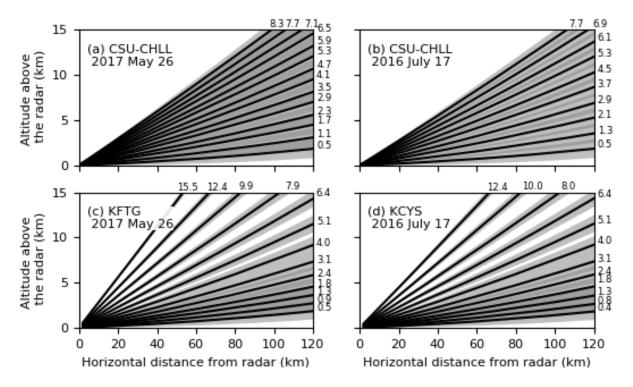


Figure 2: Radar elevation angles for both the CSU-CHILL (a-b) and NEXRAD (c-d) radars during dual-Doppler analysis times for the two C³LOUD-Ex cases. Black lines represent the center of the beams, while gray shading represents the vertical distance covered by the beams. The smaller numbers outside the panels represent the mean elevation angle used for the PPI scan.

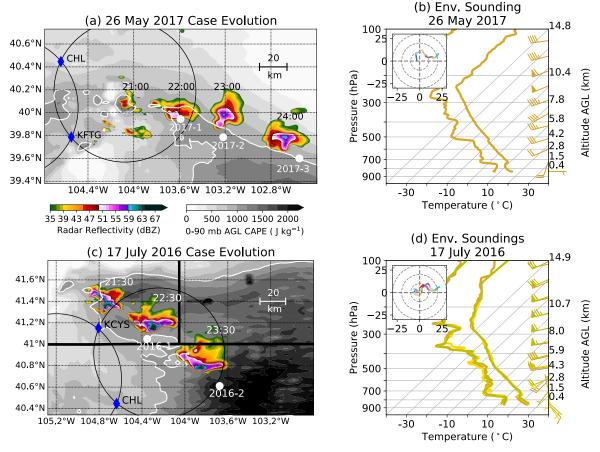


Figure 3: Case evolution and environmental soundings from the 2017 case (top row), and the 2016 case (bottom row). The white dots represent the locations where the updraft radiosondes were launched. The blue diamonds are the radar locations, and non-overlapping regions of the black circles indicate where dual-Doppler analyses are possible. The color shading shows radar reflectivity at 1 km AGL at the approximate time of radiosonde launch, gridded and interpolated from the available radars. The gray shading represents MLCAPE from the 21:00 UTC operational simulation of High Resolution Rapid Refresh (HRRR) model for both cases; 1000 J kg⁻¹ is contoured in white. The right column shows skew $T - \log p$ diagrams of the environmental radiosonde launches as described in the text. Hodographs are inlaid and the different colors within the hodographs represent 500-m increases in altitude from the surface to 6 km AGL.

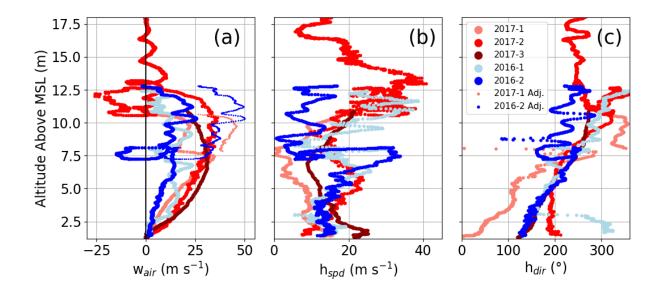


Figure 4: (a) Radiosonde w_{air} from radiosondes that sampled the two C³LOUD-Ex supercell updrafts. (b) and (c) represent the radiosondes' horizontal wind speed (h_{spd}) and horizontal wind direction (h_{dir}), respectively. In (c), 180° represents winds coming from the south. Data are only shown from the radiosondes' launch times through to when the radiosondes reached their maximum altitudes. The smaller dots for 2017-1 and 2016-2 represent w_{air} adjusted for the assumption of a burst radiosonde balloon (see Fig. 5). Radiosonde data in this figure and subsequent figures are shown at 1 Hz frequency.

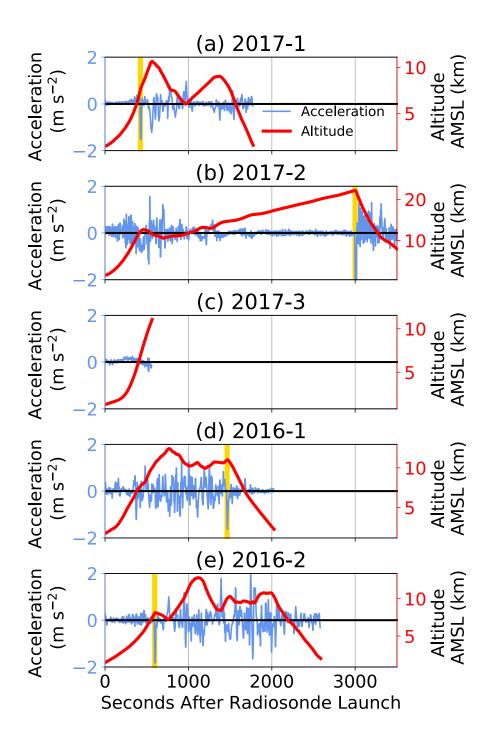


Figure 5: Radiosonde accelerations from each launch (blue, left axis) and radiosonde altitude (red, right axis) as a function of seconds since launch. Yellow vertical lines indicate the strongest negative accelerations, which were assumed to be coincident with the radiosonde balloon bursting.

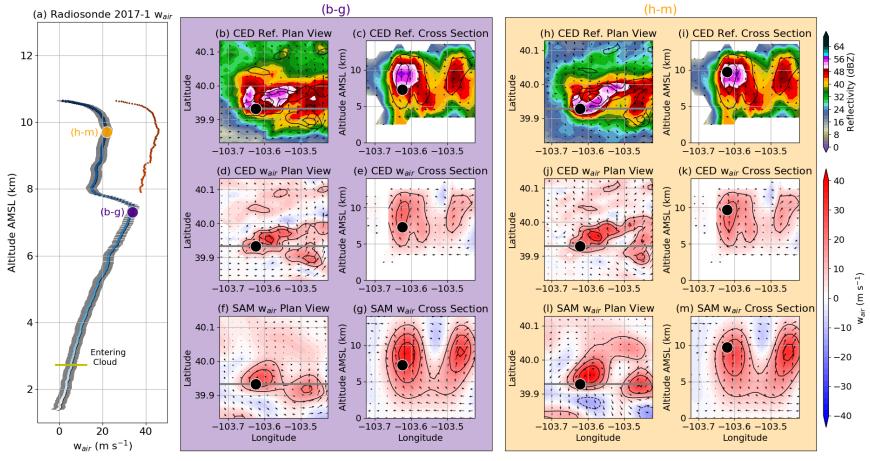


Figure 6: (a) Radiosonde w_{air} for the 2017-1 launch with uncertainty estimates (gray). The shading from light to dark blue represents the time evolution of the radiosonde from launch to maximum altitude. The smaller, red dots take into account adjustments, assuming the radiosonde balloon burst. (b-m) demonstrate the position of the radiosonde (black dots) within the storm at two different times during the radiosonde ascent. The top row shows radar reflectivity plan views and vertical cross sections, as denoted by the grey lines in the plan views. The middle row shows the plan views and cross sections of CEDRIC w_{air} , while the bottom row shows SAMURAI w_{air} . The arrows represent storm-relative winds in their respective planes, and black contours indicate 10 m s⁻¹ intervals of w_{air} , excluding the 0 m s⁻¹ contour.

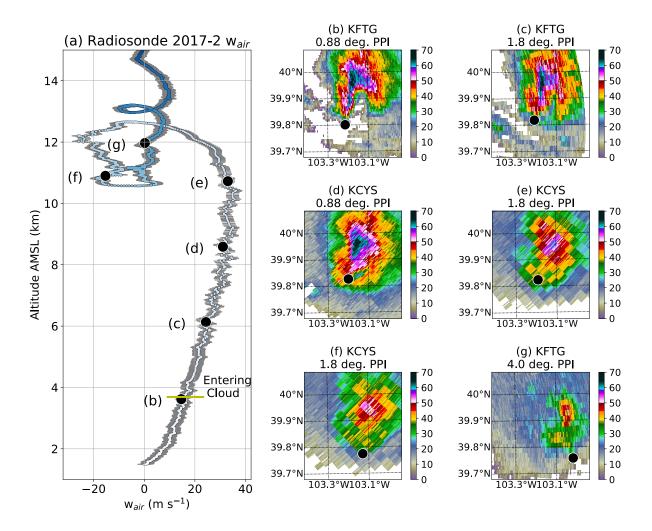


Figure 7: Radiosonde-derived w_{air} for the 2017-2 launch with uncertainty estimates (gray). The shading from light to dark blue represents the time evolution of the radiosonde from launch to maximum altitude. Panels (b-g) represents PPI scans of radar reflectivity that overlapped with the radiosonde within a 15 second window and within 500 m of the radiosonde's position, as labeled in panel (a).

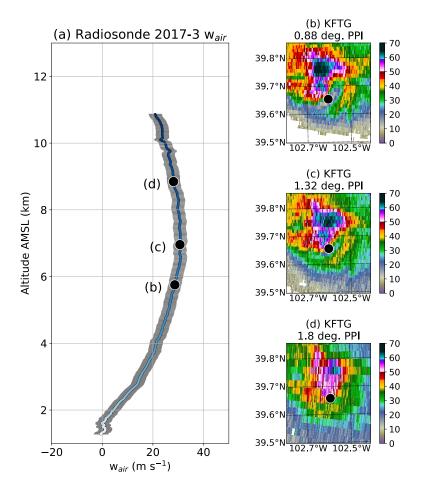


Figure 8: Same as Figure 7, but for the 2017-3 radiosonde launch.

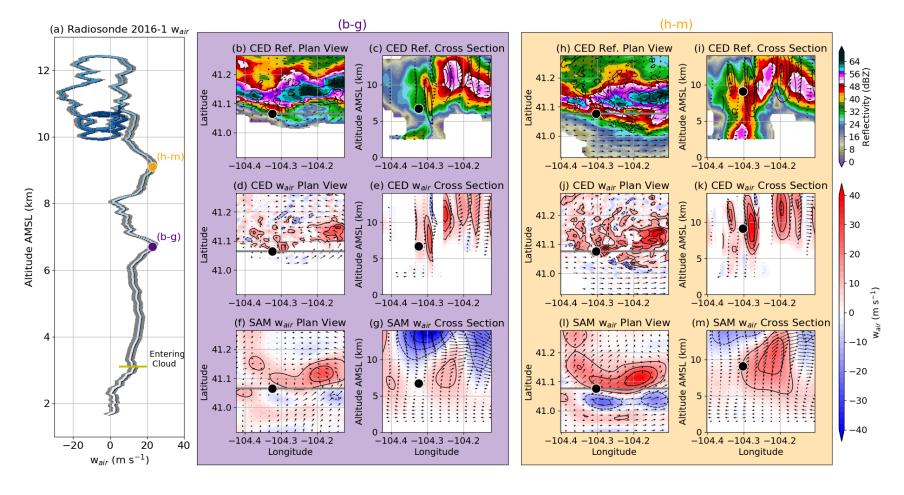


Figure 9: Same as Figure 6 but for the radiosonde 2016-1 data. The light blue to dark blue shading in (a) represents the progression of time from launch to when the balloon likely burst.

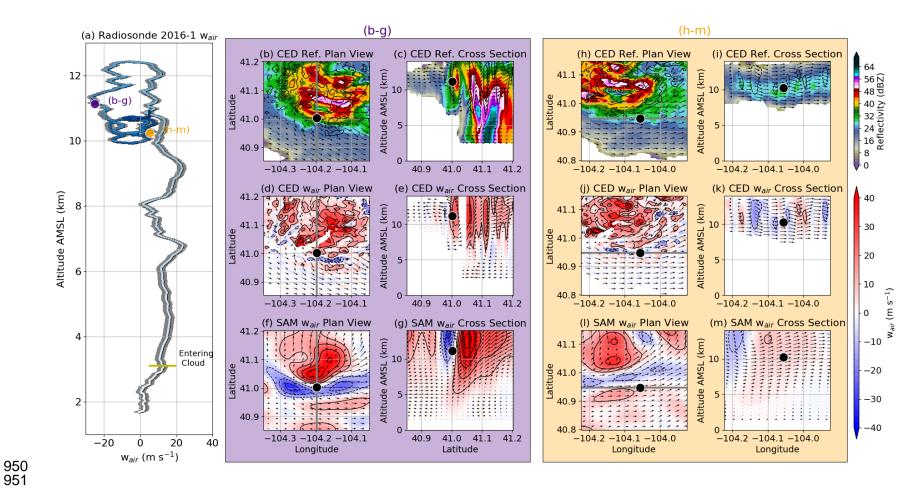


Figure 10: Same as Figures 6 and 9, but for two later times during the progression of radiosonde 2016-1.

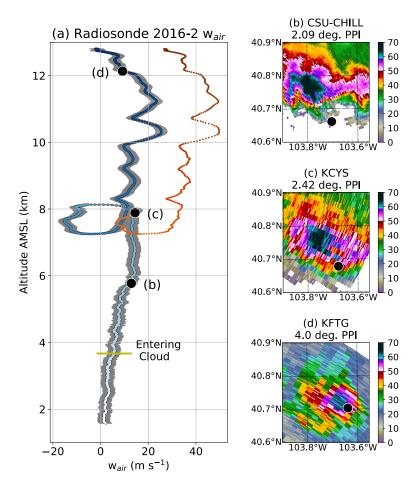


Figure 11: Same as Figures 7 and 8 but for radiosonde 2016-2. The smaller, red dots take into account adjustments assuming that the radiosonde balloon burst.

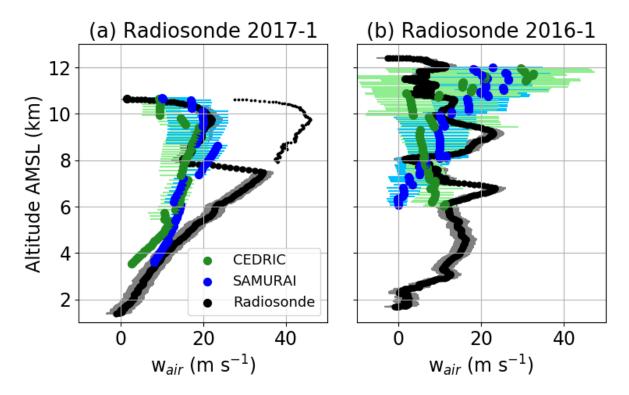


Figure 12: Comparison of radiosonde and dual-Doppler w_{air} for radiosondes (a) 2017-1 and (b) 2016-1, as described in the text. The gray range for the radiosonde data represents the quantified uncertainty in w_{air} . The green and blue dots represent the radar dual-Doppler analyses interpolated to the radiosonde position. The green and blue horizontal lines represent the range of values within 1 km in the horizontal direction of the radiosonde position within the dual-Doppler analyses.

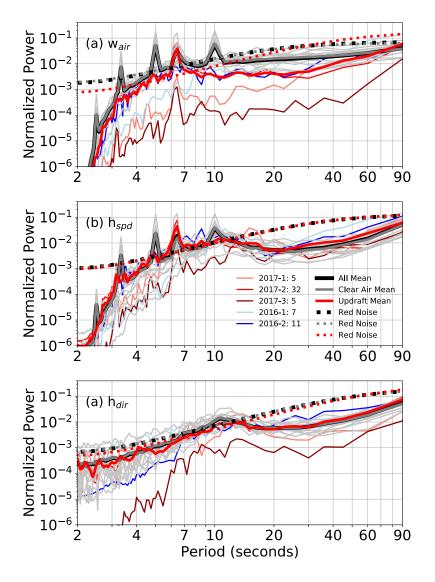


Figure A1: Mean power spectra for the 13 clear air (thin gray lines) and 5 updraft (thin red and blue lines) radiosonde launches for w_{air} , h_{spd} and h_{dir} . The data chunk that was used was 180 s, and the number of chunks that went into each radiosonde launch is shown in the legend. For the 13 clear air launches, the number of chunks varied from 18 to 49. The thick, solid black line represents the mean power spectra for all the data, while the thick solid gray and red lines represent the means of the clear air and updraft launches, respectively. Estimates of the red noise spectra are also shown as thick, dashed lines.

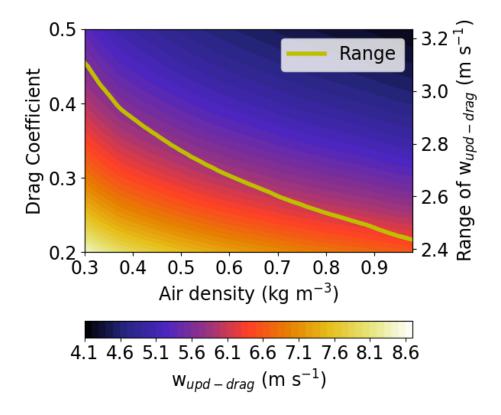


Figure A2: Terminal velocity calculations (m s⁻¹) for ascending C³LOUD-Ex radiosondes with varying drag coefficients and densities (shaded, left axis) and the range (maximum minus minimum) of terminal velocities for each density